



IFLY4 Multi-Copter User Manual



ShenZhen Idea-fly Technology Co., Ltd.

http://idea-fiy.com



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Statements

- THIS PRODUCT IS NOT A TOY!
- ➤ It is a sophisticated product for sports and leisure, and a combination of mechanics, electronics, aerodynamics and high-frequency radio technologies. The operator should follow instructions and security rules. Proper Installation and test are compulsory to avoid accidents. Inappropriate operation may cause serious damages. We are not responsible for them.
- Please read this statement carefully and use this product strictly following all these instructions .
- This product is an R/C hobby model rather than a toy. Any operation should be compliant to safety instructions, local laws and regulations. We are not liable for any behaviour against them, or any consequence caused by those behaviours.
- This product is only suitable for expert, who is definitely no younger than 12 years old.
- Please use it in the field approved by local government, laws or regulations.
- We are not responsible for any civil or criminal liabilities caused by improper operation or illegal usage.
- If you have questions about usage, operation, maintenance or any other issues, please contact local distributors.



Preface

Dear Customer:

Thanks for choosing idea-fly R/C hobby product! To handle it as fast as possible, please read all instructions carefully. In addition, please keep this manual for further reference in the future.

The flight is equipped with high-performance electronic flight controller, foldable fuselage, highly-efficient brushless motors and high-speed, silent motor governor. High-capacity Li-Poly battery supplies quite good payload ability. Additional high-performance camera mount supplies ability of aerial video and photography with camera or DV.

The fuselage is made of high-strength engineering plastics, which reduces weight and cost effectively.

It will make much more fun for your photography.



Introduction



Cool appearance and foldable design

Four low-noise brushless motors

 $\label{thm:light-performance} \mbox{Hight control system(flight controller + motor governor)} \\$

+ power connector)

Net weight: 620g (exclude radio receiver and battery)

Payload: 450g(exclude radio receiver and battery)

Single axis camera mount(additional)



Specification

size

size: 57cm X 57cm

Distance between motors:45cm

■ Height: 25.4cm

Propeller

Material: Plastic

Propeller size: 10inch * 2

Anti-rotating Propeller : 10inch

* 2

Camera Mount

 Camera Mount with vibration isolation

Material: carbon fiber

Number of axes: single axis

Bracket

High flexible plastic bracket

Weight & payload

Flight body weight: 640g

Payload: 500g

Maximum Takeoff Weight: 1,150g

Motor

Brushless Motor: (IFly2212)11.1v

Drive Configuration: direct drive for each axis

Motor Governor:10A digital governor

Working environment

Ambient Humidity: <%80

Ambient temperature: 0-60 (Celsius degrees)

Ambient wind speed: < 4m/s</p>

Power

Working voltage: 11.1v

Max working current: 20A

Warning voltage: 10.8V

Simulator: Manual mode, balance mode, hight locked mode

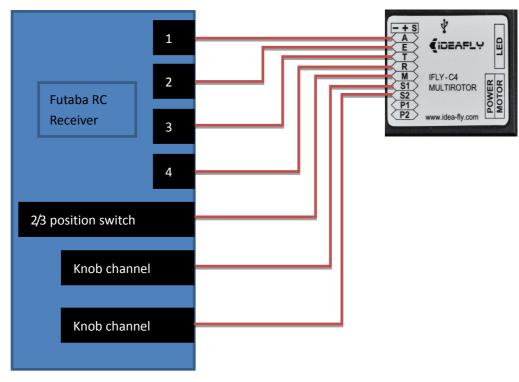


Radio transmitter

Before using IFLY4, you should connect and calibrate your radio transmitter(radio controller). IFLY4 support ordinary PWM radio transmitter like futaba\jr. IFLY4 may need at most 7 channels to achieve flying forward/backward, tilting left/right, rotating around z axis, controlling throttle, switching flight modes, tuning camera mount. To fly it, you need at least 5 channels.

Caution: No mixtured throttle mode.

Taking Futaba receiver as an example.





Connecting radio receiver

- A: Connecting to AILERON channel of receiver
- E: Connecting to **ELEVATOR**channel of receiver
- T: Connecting to THROTTLEchannel of receiver
- R: Connecting to RUDDERchannel of receiver
- **F:** Connecting to a 3-positions channel, this will be used to choose flight modes. Please refer to 'flight modes' part.
- **S1:** Connecting to another channel which will be used to change pitch angle of camera mount
- **S2:** Connecting to another channel which will be used to change roll angle of camera mount
- P1: Connecting to servomotor which controls pitch angle of camera mount
- P2: Connecting to servomotor which controls roll angle of camera mount

Calibrate the radio transmitter

IFLY4 support ordinary PWM radio transmitters. You should calibrate range of joysticks, otherwise you can not start the flight or may cause accident. Please refer to "Transmitter Calibration" part.

Tuning angles of camera mount

IFLY4 supports 2-axes(pitch and roll) camera mount with vibration isolation and angle tunning function. Dedicated smoothly output control algorithm provide fine vibration isolation quality during photographing.



Tunning pitch angle of camera mount

You need connect corresponding channel of receiver to S1 port of IFLY4 flight controller, and connect pitch servomotor to P1 port of IFLY4.

Tunning roll angle of camera mount

You need connect corresponding channel of receiver to S2 port of IFLY4 flight controller, and connect pitch servomotor to P2 port of IFLY4.

Tunning control parameters of camera mount

IFLY4 supplies complete parameter tunning interface of camera mount control. Please refer to " camera mount control" part.

Power supply

IFLY4 support full voltage transformation, you just need one 3-cell Li-battery to power it.

Low power alert

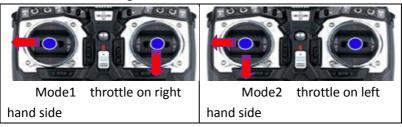
IFLY4 has low power alert function. When voltage of battery goes less then 10.8v, the speaker will beep and led will turn on. You should turn off the flight and exchange your battery.



Turn on the flight

Push the throttle stick will not start the flight, you should follow these steps instead.

- 1: pull the throttle joystick down to lowest position;
- 2:pull the rudder joystick to the left position;
- 3: motors start running at low speed. If this does not work, please check transmitter channel settings or recalibrate the transmitter.



Caution:

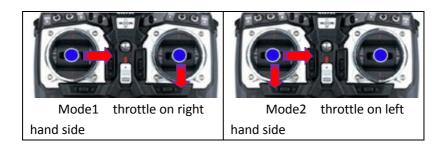
Do place the flight stationarily when you start it, otherwise IFLY4 can not work well.



Turn off

There are 2 ways to shut the flight down

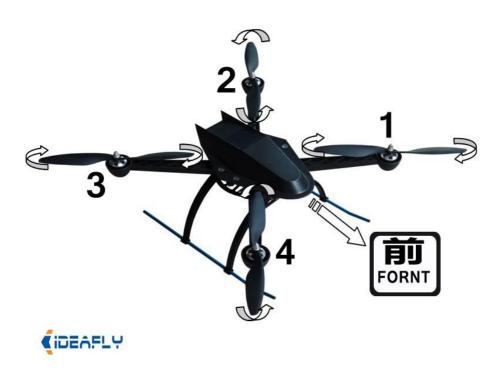
- 1: put the throttle joystick down to the lowest position and hold it on for more than 5 seconds, the flight will shutdown;
- 2: The following steps will shutdown power immediately:
 - 1: put th throttle joystick down the lowest postion;
 - 2: pull the rudder stick to right hand side.





Fixing propellers

IFLY4 need 10" clockwise/counter-clockwise propellers. Please fix them under guidance of following steps, otherwise the flight will not work.





> 1st step: fasten propeller on motors



> 2nd step: put motor shaft through the hole of propeller clamp



3rd step: screw up propeller clamp with screw driver.



桨夹安装

Caution: Pls check whether propeller is fasten firmly before every flight.



Control modes

IFLY4 support manual, balance, hight locked modes. You can identify flight mode through shining state of led under motor. IFLY4 support balance and hight locked modes at default, manual mode can only be turn on by computer software.

State of mode:

- 1: manual mode, led blinks one time and turn off for a little while;
- 2: balance mode, led blinks two times and turn off for a little while;
- 3: hight locking mode, led blinks three times and turn off for a little while.

To switch flight control modes, you need connect a 2 or 3 position channel of receiver to port **M** of flight controller.



Manual mode

IFLY4 can not auto level itself at this mode, you should adjust transmitter all the time to keep the flight under control.

Balance mode

IFLY4 will auto level itself, and you can change tilt angles of the flight by



joysticks. If you release joysticks, it will auto level itself. However, you should adjust the throttle joystick to maintain its height.

Height locked mode

At this mode, IFLY4 will auto level and keep its height locked. Once the throttle joystick is within the hover range, the flight will keep its height. (hover range can be adjust by computer software.)

Firmware

You can update IFLY4 with latest firmware to achieve best performance. Please refer to "Firmware" Part.



Working state checking

- 1. After propellers are correctly installed, power on flight and check joystick movement.
- 2. level flight on the ground, and put transmitter besides it.
- 3. power on the flight, hold the flight by the left hand **《△Do not touch propellers** pull throttle stick up to 20%.
- 4. roll aileron, elevate, rudder joystick slightly to check whether the flight performs correctly
- if the flight does not performs correctly, please check rotating direction of propellers / motors, wire connection between receiver and flight controller
- 6. hold the landing gear of the flight, lift it up, Do please not touch any motor or propeller during this procedure
- 7. push throttle up to 20% of its range
- 8. title the flight in aileron/elevate/rudder direction to see whether the flight can level all by themselves
- 9. If the flight can not get level themselves, please check connecting wire of flight controller, or rotating direction of motors and propellers
- 10. After all these checked, we are ready to fly



Operation

Mode1 《throttle on right-hand-side》 just for reference

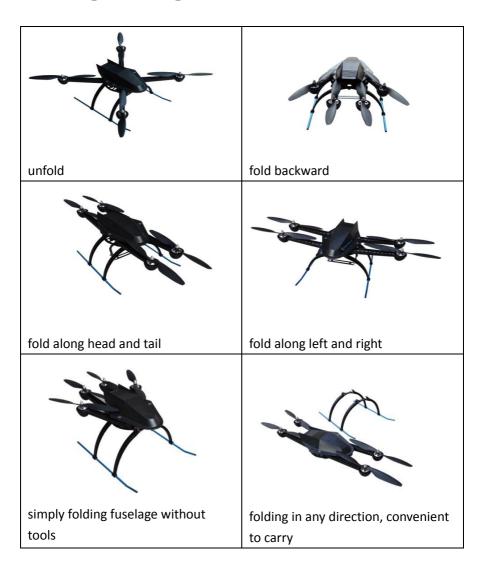
THOUGH WITHOUT	Wodel \(\text{tillottle off right-riand-side}\) Just for reference				
ир			push up right stick		
down			pull down right stick		
turn left			turn left- stick to left		
turn right			turn left- stick to right		
head down/go forward			push left stick up		

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head up/go backward		pull left- stick down
tilt left		turn right- stick to left
tilt right		turn right- stick to right



Fuselage folding

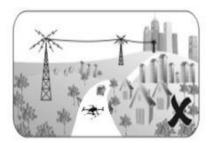




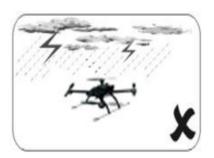
Warning and Caution

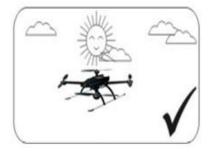
Far away from human or building

Rotating propeller is dangerous to human; make sure fly it far away from crowds. Improper installation, broken components or abnormally working controller, even slight mistake of operation may cause serious accident. Pilot should keep it safe, and be ware of safety responsibility.









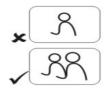
Flying field should be large enough, we recommend no less than 100m*100 m, far away from crowds, high building, high-voltage towers, woods or any other things, which may cause accidents or damages.



Do not fly it alone

Novices should be guided and supervised by experts. Do not fly it all by yourself alone.

Practice on simulator software may be helpful.



Far away of running components

Do be away from any operating components, especially rotating propellers.



Avoid moist environment

The flight is equipped with sophisticated electronic device; do not fly it in moist environment. Do not operate it in rain, snow, lightening storm, fog, hail or gust more than level 3. Present electronic device from water.



Far away from heat or radiation

Fuselage is composed of engineering plastic; please keep it far away from heat source or radiation.





Maintenance

- ➤ IFLY 4 quad-copter is composed of sophisticated components. Do please make sure everyone works well to achieve best performance.
 - Improper maintenance may cause accidents or damages. We strongly recommend that maintain this suite regularly.
- ➤ If motors do not work well, serious vibration may emerge. Please check propellers work well or fixed firmly, replace them if necessary
- Make sure all wires are connected firmly, especially those connecting governor and motor, in case of accidents during flight
- To protect the flight, do not expose the flight in moist atmosphere or strong sunshine or static electricity higher than 64V
- Check screws, which fix fuselage, motors, and propellers regularly. We recommend to use middle-strength screw glue



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